## :hager



## 1

## Preliminary operations

Check the following upon delivery and after removal of the packaging:

- Packaging and contents are in good condition.
- The product reference corresponds to the order.
- Contents should include:
- 1 HZI855 ATSE controller
- 4 door mounting screws
- 4 backplate mounting feets
- Accessory: IP65 gasket: ref. HZI501

This Quick Start is intended for personnel trained in the installation and commissioning of this product. For further details refer to the product instruction manual available on www.hager.com.
This product must always be installed and commissioned by qualified and approved personnel. Maintenance and servicing operations should be performed by trained and authorised personnel. Do not handle any control or power cables connected to the product when voltage may be, or may become present on the product, directly through the mains or indirectly through external circuits.
Always use an appropriate voltage detection device to confirm the absence of voltage.
Ensure that no metal objects are allowed to fall in the cabinet (risk of electrical arcing).
Failure to observe good enginering practises as well as to follow these safety instructions may expose the user and others to serious injury or death.
© Automatic Transfer Switching Equipment Controller

## Installation and commissioning controller




## + 10

## Networks

## Type of networks

Power Supply:
The HZI855 controller is Self-powered from the voltage sensing of any available source, and may also be powered (as a backup from saved source) from the DC auxiliary power input (24 VDC).

Dual Power Supply/Sensing
The HZI855 controller will be automatically supplied from the voltage sensing connectors of both sources thanks to an internal DPS (dual power supply) module that in case main source failure, will immediately switch to the secondary source supply the device.
NOTE: The nominal auxiliary power supply feeding the sensing terminals must be within the limits of $88 \Rightarrow 576$ VAC.




NOTE: The HZI855 must include a SCPD such as fuses on each phase of the voltage sensing control wiring. 1A gG fuses are recommended.

## Metering and sensing detail

NETWORK TYPE

|  | $1 \mathrm{P}+\mathrm{N}$ | 2 P | $2 \mathrm{P}+\mathrm{N}$ | 3P | $3 \mathrm{P}+\mathrm{N}$ | $3 \mathrm{P}+\mathrm{N} / 1 \mathrm{P}+\mathrm{N}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Source 1 | 1 phase 2 wire | 2 phase 2 wire | 2 phase 3 wire | 3 phase 3 wire | 3 phase 4 wire | 3 phase 4 wire |
| Source 2 |  |  |  |  |  | 1 phase 2 wire |

Loss of neutral: will be detected in all cases except for balanced networks with balanced loads.
In Breaker mode: the use of undervoltage release (see wiring diagram) can prevent this situation.

HZI855 and HIB4xxM
for network/network application type

for network/genset application type


Default configuration for Inputs and Outputs for "HIB4xxM" mode:
IN1: Switch is in position 1
IN2: Switch is in position 2
IN3: Switch is in position 0
IN4: Inhibit
IN5: Manual restransfer
IN6: RTSE in manual
OUT1: Order to switch in position 1
OUT2: Order to switch in position 2
OUT3: Order to switch in position 0
OUT4: S1 Available
OUT5: S2 Available
OUT6: Order to start Genset

* The use of this input is optional, when used IN6 should be configured to "COVER OPEN" in mode "NC".
This configuration is defined with source I as the priority source. This diagram covers most application cases, the inputs and outputs are configured by default for this installation.

HZI855 with MCCB for network/network application type


Note: indicated references are used for MCCB x250/P250 and x630/P630.
Default configuration for Inputs and Outputs for "Breaker" mode:
IN1: Breaker 1 is in position ON
IN2: Breaker 2 is in position ON
IN3: Breaker 1 is in position OFF
IN4: Breaker 2 is in position OFF
IN5: Breaker 1 is in position TRIP
IN6: Emergency stop
OUT1: Order to close Breaker 1
OUT2: Order to close Breaker 2
OUT3: Order to open Breaker 1
OUT4: Order to open Breaker 2
OUT5: NONE
OUT6: Order to start Genset
IN2: Breaker 2 is in position ON

HZI855 with MCCB
for network/genset application type


This configuration is defined with source I as the priority source. This diagram covers most application cases, the inputs and outputs are configured by default for this installation, the actions of the controller will be:

- In the event of neutral loss from source I: the undervoltage coil will trip the circuit breaker for source I making it unavailable (ALarm contact on input 5) to switch to secondary source II.
- In the event of tripping via the emergency stop button: the undervoltage coil will trip the circuit breaker of the source I making it unavailable (ALarm contact on input 5) BUT the control ler will switch to " total inhibition "(input 6 activated), that is to say that the load will no longer be supplied without manual intervention on the controller in order to acknowledge this fault.
After acknowledgment, the controller will switch to priority source I if available, otherwise to secondary source II.


Note: indicated references are used for ACB hw+.
Default configuration for Inputs and Outputs for "Breaker" mode:
IN1: Breaker 1 is in position ON
IN2: Breaker 2 is in position ON
IN3: Breaker 1 is in position OFF
IN4: Breaker 2 is in position OFF
IN5: Breaker 1 is in position TRIP IN6: Emergency stop
OUT1: Order to close Breaker 1
OUT2: Order to close Breaker 2
OUT3: Order to open Breaker 1
OUT4: Order to open Breaker 2
OUT5: NONE
OUT6: Order to start Genset

This configuration is defined with source I as the priority source. This diagram covers most application cases, the inputs and outputs are configured by default for this installation, the actions of the controller will be:

- In the event of neutral loss from source I: the undervoltage coil will trip the circuit breaker for source I making it unavailable (ALarm contact on input 5) to switch to secondary source II.
- In the event of tripping via the emergency stop button: the undervoltage coil will trip the circuit breaker of the source I making it unavailable (ALarm contact on input 5) BUT the control ler will switch to " total inhibition "(input 6 activated), that is to say that the load will no longer be supplied without manual intervention on the controller in order to acknowledge this fault.
After acknowledgment, the controller will switch to priority source I if available, otherwise to secondary source II.


Note: indicated references are used for ACB hw+.

Default configuration for Inputs and Outputs for "Breaker" mode:
IN1: Breaker 1 is in position ON
IN2: Breaker 2 is in position ON
IN3: Breaker 1 is in position OFF
IN4: Breaker 2 is in position OFF
IN5: Breaker 1 is in position TRIP
IN6: Emergency stop
OUT1: Order to close Breaker 1
OUT2: Order to close Breaker 2
OUT3: Order to open Breaker 1
OUT4: Order to open Breaker 2
OUT5: NONE
OUT6: Order to start Genset

This configuration is defined with source I as the priority source. This diagram covers most application cases, the inputs and outputs are configured by default for this installation, the actions of the controller will be:

- In the event of neutral loss from source I: the undervoltage coil will trip the circuit breaker for source I making it unavailable (ALarm contact on input 5) to switch to secondary source II.
- In the event of tripping via the emergency stop button: the undervoltage coil will trip the circuit breaker of the source I making it unavailable (ALarm contact on input 5) BUT the control ler will switch to " total inhibition "(input 6 activated), that is to say that the load will no longer be supplied without manual intervention on the controller in order to acknowledge this fault.
After acknowledgment, the controller will switch to priority source I if available, otherwise to secondary source II.


## Controller wiring

Bottom view


1. Voltage sensing source 1.
2. Voltage sensing source 2 .
3. RS485.
4. RTC battery

Top view
(9)

5. Optional Aux. Supply 24 VDC.
6. Programmable INPUTS.
7. Latching relays
.
9. Config USB.
Cabling Output relays 1-4
Cabling Output Latching relays 5 \& 6

| Controller config | STATE (relay) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Output configured as NO NO by default | OFF (not active) | Open | Closed | Open | Closed |
|  | ON (activated by firmware) | Closed | Open | Closed | Open |
|  | Controller not supplied | Open | Closed | Closed* | Open* |
| Output configured as NC | OFF (not active) | Closed | Open | Closed | Open |
|  | ON (activated by firmware) | Open | Closed | Open | Closed |
|  | Controller not supplied | Open | Closed | Closed* | Open* |

* HZI855 controller includes two bi-stable relays with backup energy, when the controller loses all sources of power supply outputs 5 and 6 will automatically activate (NO contact will close and NC contact will open). This is a safety feature designed to ensure power availability to the load in Main-Genset or Genset-Genset application by forcing generators to start in case of total power loss. It is highly recommended to configure the outputs 5 and 6 to take benefit from this function.

| TYPE | TERMINAL ${ }^{\circ}$ | DESCRIPTION | BY DEFAULT | CONFIGURATION CHANGES WHEN CHANGING RTSE TECHNOLOGY |  | CHARACTERISTICS | RECOMENDED CROSSSECTION |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Breakers | HIB4xxM | Contactors |  |  |
| Sensing source 1 | $\begin{gathered} \text { SOURCE } 1 \\ \text { L1/L2/L3/N } \end{gathered}$ | Voltage sensing inputs source 1 \& voltage supply (L1-L2) | - | - | - | Sensing voltage 50-575VAC P-P | $0.75-2.5 \mathrm{~mm}^{2}$ |
| Sensing source 2 | SOURCE 2 L1/L2/L3/N | Voltage sensing inputs source 2 \& voltage supply (L1-L2) | - | - | - | Supply voltage (L1-L2) $88-575 \mathrm{VAC} 50 / 60 \mathrm{~Hz}$ $(+-10 \%)$ Ui $=600 \mathrm{~V}$ | Tightening torque $0.5-0.6 \mathrm{Nm} / 4.4-5.3 \mathrm{Lb} . \mathrm{in}$ |
| Inputs | 71 | \|N1: programmable input | Breaker 1 is in position ON | Switch is in position 1 | Contactor 1 is in position ON | Do not connect to any power supply from terminal 70 common point. <br> Configurable type NO or NC - NO by default | $\begin{gathered} 0.5-2.5 \mathrm{~mm}^{2} \\ \text { Tightening torque } \\ 0.5-0.6 \mathrm{Nm} / 4.4-5.3 \mathrm{~L} . \mathrm{in} \end{gathered}$ |
|  | 72 | IN2: programmable input | Breaker 2 is in position ON | Switch is in position 2 | Contactor 2 is in position ON |  |  |
|  | 73 | IN3: programmable input | Breaker 1 is in position OFF | Switch is in position 0 |  |  |  |
|  | 74 | IN4: programmable input | Breaker 2 is in position OFF | Inhibit | - |  |  |
|  | 75 | IN5: programmable input | Breaker 1 is in position TRIP | Manual retransfer | - |  |  |
|  | 76 | IN6: programmable input | Emergency stop | RTSE in manual | - |  |  |
|  | 70 | Common point for inputs |  |  |  |  |  |
| Outputs |  | Logic | Impulse | Impulse | Maintained | Dry contacts 8A/277VAC50/60 Hz 5A/24VDC <br> Configurable type NO or NC - NO by default | $\begin{gathered} 1.5-2.5 \mathrm{~mm}^{2} \\ \text { Tightening torque } \\ 0.5-0.6 \mathrm{Nm} / 4.4-5.3 \mathrm{~L} . \mathrm{in} \end{gathered}$ |
|  | 12/14/11 | OUT1: programmable output | Order to close Breaker 1 | Order to switch in position 1 | Order to close Contactor 1 |  |  |
|  | 22/24/21 | OUT2: programmable output | Order to close Breaker 2 | Order to switch in position 2 | Order to close Contactor 2 |  |  |
|  | 32/34/31 | OUT3: programmable output | Order to open Breaker 1 | Order to switch in position 0 | - |  |  |
|  | 42/44/41 | OUT4: programmable output | Order to open Breaker 2 | S1 Available | - |  |  |
| Latching relays |  | Logic | Impulse | Impulse | Maintained |  |  |
|  | 52/54/51 | OUT 5: genset start relay / programmable output | - | S2 Available | - |  |  |
|  | 62/64/61 | OUT 6: genset start relay/programmable output | Order to start Genset | Order to start Genset | - |  |  |
| Serial connection | RS485 | Connection RS485 <br> - : negative terminal of RS485 bus <br> +: positive terminal of RS485 bus NC: ground | - | - | - | RS485 bus insulated | Modbus cable $25 \mathrm{~m}=\mathrm{HTG} 485 \mathrm{H}$ LiYCY sheilded twisted pair 0.14 to $1.5 \mathrm{~mm}^{2}$ Tightening torque $0.22-0.25 \mathrm{Nm} / 1.9-2.2 \mathrm{Lb} . i n$ |
| Aux power supply | 81/82 | -: negative terminal for aux supply <br> + : positive terminal for aux supply | - | - | - | 12-24VDC | Tightening torque $0.5-0.6 \mathrm{Nm} / 4.4-5.3 \mathrm{Lb} . \mathrm{in}$ |



SMART WIZARD CONFIG:
When powered for the first time the controller will prompt the user to configure using the wizard.
To access the wizard input code 1000 then the configuration will go as follow:


## Visualization



- Short press on this button to cycle the dashboards.



## Menus \& programming

|  | MAIN MENU |
| :---: | :---: |
| CONTROL |  |
| 目 | LOG |
| .illl | STATISTICS |
| 岃 | GENSET SCHEDULER |
| I! | PARAMETERS |
| fn | SPECIFIC FUNCTIONS |
| $\stackrel{0}{\circ}$ | MAINTENANCE |
| (i) | ABOUT |



- Short press on this button to go back one level. - Long press to access the menus.

To access to certain functions, you may be asked for a password. By default, this is 1000 .





There are several events that can cause a Fault on the controller. Unlike the alarms, the faults are not user-selectable, they will always be considered and actions will take place as follows:

| FAULT | DESCRIPTION (CAUSE) | ACTIONS | ACKNOWLEDGE / CLEARED | $\begin{gathered} \text { FAULT } \\ \text { LOG } \end{gathered}$ | POP-UP | FAULT LED | OUTPUT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Unexpected Transfer | The controller receives a feedback/return from the switch without sending any order (auto or manu). Also if loss feedback of current position. | Mode stays the same. Controller will start retries if position is unknown. If a position is reached, no retry takes place. | Can also be cleared through display or through RST - Reset Fault input. | Yes | Yes, "Unexpected Transfer" | BLINKS (priority) | FLT - Fault active |
| Failed to Transfer | Position not reached after an order sent by controller (auto or manu) or loss of feedback of the new source after sending a transfer command. | Mode stays the same. Controller will start retries. | Automatically cleared if the requested position is reached or cleared through display or through RST - Reset Fault input. | Yes | Yes, "Failed to transfer" | BLINKS (priority) | FLT - Fault active |
| Max operation per minutes reached | If the controller performs 10 operations in less than 1 minute (by default) (automatic or controlled/manual) | Mode stays the same. During a timer, the controller will not do or allow any operation. | Automatic after the 1 minute (configurable through software)(value is dynamic). | Yes | Yes, "Max operations per minutes reached" | FIXED (non-critical) | FLT - Fault active |
| Max password attempts reached | User tries to enter a profile password more than X times set in the maintenance menu (by default 10 attempts) | Mode stays the same. Can't enter any password during $X$ time set in the maintenance menu (by default 2 minutes) | Automatic after the set timeout (maintenance mode). | Yes | Yes, "Max number of tries reached, please wait: X s" | FIXED (non-critical) | FLT - Fault active |
| Genset Failstart | Controller tries to start a genset (as configured) and after the genset start delay, the genset doesn't start (controller doesn't see the source on) | Mode stays the same. Genset start relay remains active unless other source is available. | Automatic if genset starts or if source is set as Main/Utility. | Yes | Yes, "Engine fail to start" | BLINKS (priority) | FLT - Fault active |
| External fault | If an input is selected as FTE <br> - External Fault and becomes active | Switch goes to position 0 /center-off directly without timers and the mode is set to Partial Inhibit (genset starts if needed). | Input mustn't be active and reset by user is requested (by RSTReset Fault input or through display. | Yes | Yes, "External fault" | BLINKS (priority) | FLT - Fault active |

For faults with pop-up, the pop-up will be cleared when fault will be cleared or by pressing any button on the front face of the controller. The total number of faults logged on the controller is dynamic, as the total number of "faults + alarms" is 100 (not including the events, which are 300 ) and uses a FIFO ordering.

To clear Faults through the display, it is possible inside the LOG / FAULTS menu with the option "PRESS OK TO RESET FAULTS", using the configurator profile password (1000). There is also a shortcut by holding the -8-button for 1.5 s and validating on the pop-up that appears. If the fault is still active, it will be inside the log "IN PROGRESS", but the fault LED and output will be off. If the faults are not active any more, they will be logged in the "HISTORY" log. This way to clear the fault will be automatically proposed by the controller through a pop-up:


